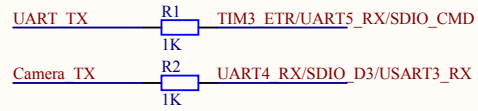
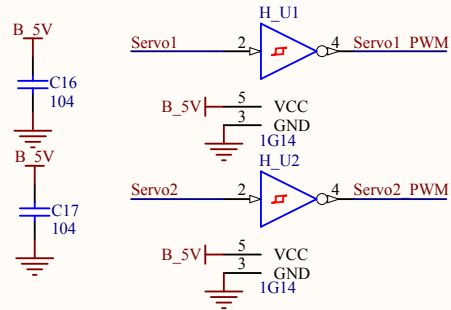


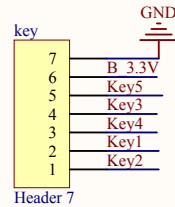
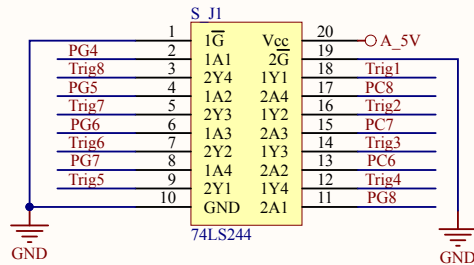
逻辑电平转换 (3.3V<->5V) A->B(DIR-H)



UART_RX UART5_TX/SDIO_CK/USART3_CK
Camera_RX UART4_TX/SDIO_D2/USART3_TX

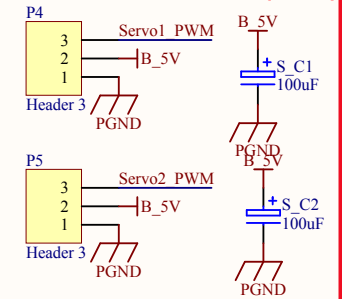
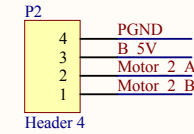
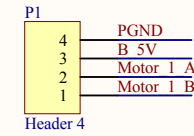


Echo1	PD10
Echo2	PD11
Echo3	PD12
Echo4	PD13
Echo5	PD14
Echo6	PD15
Echo7	PG2
Echo8	PG3

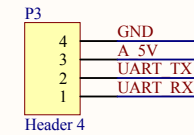


电机控制信号PPMx4/PWMx4/USARTx2(5V)

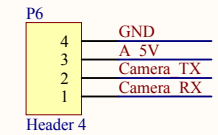
舵机控制信号PWMx2 (5V)



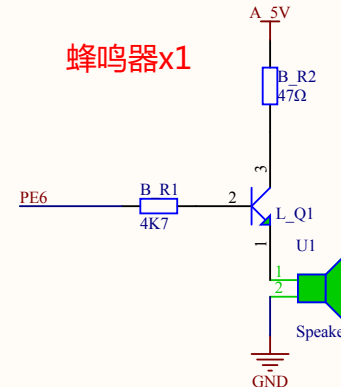
串口x1



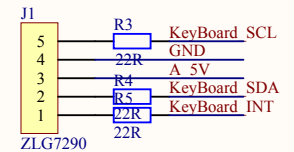
摄像头x1 (串口)




蜂鸣器x1



KeyBoardx1



Title <i>Interface</i>			* * * *	
Size: <i>A4</i>	Number:*	Revision:1.0		
Date: 2017/4/10	Time: 16:10:38	Sheet3 of 3		
File: E:\01\TAC主控\RobotControlBoard V3.0\RobotControlBoard V3.0\Interface V3.0\SchDoc				

